

Characteristics:

Main function :

The EGC “Sirius” actuator allows the rotation of a headlamp light unit in order to optimize the light distribution in the curves according to a signal coming from the steering wheel.

It has an integrated electronic driving unit communicating with the headlamp through Lin bus protocol. Its motor is a 2 phase bipolar stepper.

It has an integrated position sensor and a triple play compensation system.



Performance:

Performance (typical, other requirements can be passed)

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|--------------------------|------------------------------|
| ■ Voltage range (V) | 10 to 16 |
| ■ Speed range (°/s) | 14 to 25 |
| ■ Nominal torque (Ncm) | >50 at 13V / 23°C / 729Hs/s |
| ■ Minimal torque (Ncm) | >35 at 10V / -40°C / 729Hs/s |
| ■ Maximal torque (Ncm) | <70 at 16V / 23°C / 729Hs/s |
| ■ Angle range (°) | +/-20 |
| ■ Resolution (°/HS) | 0.0354 |
| ■ Temperature range (°C) | -40 / +105 |
| ■ Duty cycle (%) | 40 |
| ■ Protection | IP40 |
| ■ Angular play (°) | <0.65 under 8Ncm |
| ■ Weight (g) | 100 |

Electrical connexion and control

| | |
|-----------------|---|
| ■ Motor type | 2 phase bipolar stepper motor |
| ■ Communication | Single Wire Lin bus (Lin 2.2) |
| ■ Driver | Onsemi NCV70628 |
| ■ Connexion | JST XA7 pins (3 not used) |
| ■ Solder | Leadfree |
| ■ Reference run | Managed by internal sensor. No referencing on mechanical stop |
| ■ EMC | Specific test plan per OEM specification |

Design features(see drawing for details)

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|-------------------------|--|
| ■ Fixation on headlamp | By screws : 5 locations possible, minimum 3 including 2 central. |
| ■ Installation position | Reversible |
| ■ Location | Internal to headlamp below optical unit |
| ■ Dimensions (mm) | 78x89x29 (see drawing) |
| ■ Option | Direct driving (no Lin bus) |