## **UCC1/7**

Dimensions (mm)	Ø 28 x 31
Travel (mm)	10/13
Voltage (V) **	12–230
Speed (mm/s) 50 Hz 60 Hz	4.16 5
Max. Force (N)*	48



Depends on winding, frequency and lifetime required. Values for connector versions (C, D) / lead wire versions (N) up to 20 % lower. Driving against mechanical end stops is not permissible due to the risk of jamming. JE will not be responsible for product warranty or any liabilities associated with the application of drive against end stop. Radial forces on the shaft will reduce life time and performance.

Note: All force and power output values are minimum values, at rated voltage and motor temperature 23°C.

### Standard Data

Climatic class wide-spread according to DIN IEC 60721-2-1: 2015

Ambient temperature operation °C -15 ... +60 Ambient temperature storage °C -20 ... +100 Thermal resistance at f=0 R<sub>therm</sub> 29 K/W

Thermal class 130 (B) according to DIN EN 60085: 2008

Winding coil temperature increase K 60 standard Approval Mounting any position

Electrical connection connector type B, C, D, N

Protection IP40 according to DIN EN 60529: 2014

Weight

Rotor stalling motor can be stopped when voltage is applied, without being overheated

Bearings ball bearing

# **Order Reference**

Туре	Synchr	ronous Motor			UCC	- 1	13	į	Ν	- 1	B4	D	1E					
Configuration	13	standard magnet	73	stronger magnet														
Approval	N																	
Voltage/frequency		see next pages																
Connection	B, C D	see next pages "Connect	ion Types"															
Shaft	1E	Travel 13 mm ± 0.7 mm (	other standa	ard shafts see under dim	ensions)													



All specifications are representative only and maybe subject to variation. For confirmation of values, please contact Johnson Electric. Please also read "Saia Motors Important Notes" on catalog or at www.johnsonelectric.com/SaiaMotorsNotes

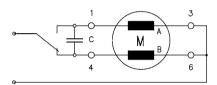
<sup>\*\*</sup> regard circuit diagram and connector type

# LICC

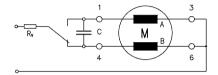
# **Technical Data**

Rated frequency	Axial speed Tolerance of voltage	Hz mm/s	50 4.16 standard power supply system +10% / -10%					
	Linear travel max.	mm	•					
	Axial play at ± 20 N force Winding temperature T <sub>max</sub>	mm	< 0.25 130					
	Rated voltage U <sub>N</sub>	V	12	24	110 <sup>1)</sup>			
	Duty cycle	%	100	100	100			
	Resistance R <sub>20</sub>	Ω	53	210	5000			
	Capacitor C <sub>50</sub> Winding code	μF/V ±10%	18/20 B1	4.7/40 B4	0.22/200 C8			

Circuit diagram Parallel circuit 12 V, 24 V, 48 V

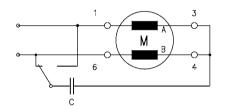


Parallel circuit 230 V (only for connector N) with 110 V motor and resistor  $R_{V}$ 

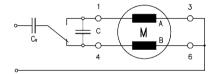


 $R_V = 5.6 \text{ k}\Omega, 3 \text{ W}$ 

Series circuit 110 V (only for connector N)



Parallel circuit 230 V (only for connector N) with 110 V motor and capacitor  $C_{V}$ 



 $C_V = 0.33 \ \mu F, 250 \ VAC$ 

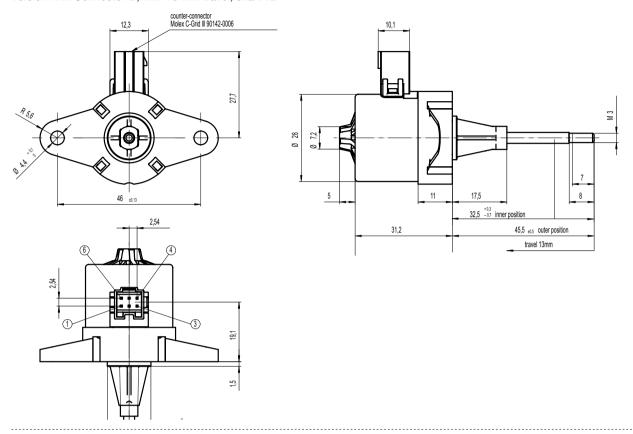
switch to

- 1 Pull (in)
- 4 Push (out)
- 6 Push (out) (for series circuit)

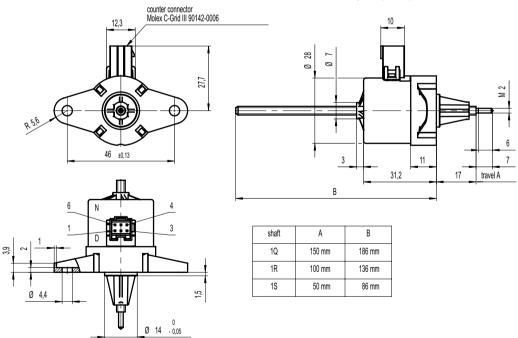
110 V version available with 150 mm lead wires AWG26 only Standard versions:

Order code
UCC13NC8N1EZ4
UCC13NC8N1SZ4
UCC13NC8N1RZ4
UCC13NC8N1QZ4

## Dimensions Version with Connector D, with 13 mm travel, shaft 1E



Version with Connector D, with 50..150 mm travel, shaft 1R, 1S, 1Q - only for pull operation



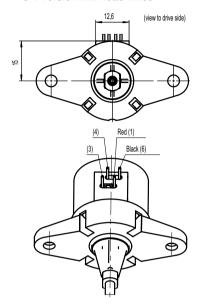
#### Please note:

The linear motor with non-captive shaft needs an external antirotation fixation and guidance. The antirotation is to produce the linear movement.

Application design of the guidance has to consider a maximum tolerance of 0.2° from the ideal axis.

The shaft guidance has strong influence on motor live time.

## Dimensions 110 V version with lead wires



different lead colours for 110V (230V) for rotary synchronous motors in serials circuit

#### Force with shaft 1E

		connecto	r version	lead wire version				
		50 Hz	60 Hz	50 Hz	60 Hz			
UCC1	100 %	33 N	35 N	26 N	29 N			
0001	30%	39 N	41 N	31 N	34 N			
UCC7	100 %	39 N	41 N	32 N	35 N			
0007	30%	47 N	48 N	38 N	42 N			