

UCE1/7; UCE2/8

Dimensions (mm)	∅ 28 x 31
Travel (mm)	10/13
Travel per step (mm)	0.021
Speed (mm/s) at 200 Hz	4.16
Max. Force (N)*	80



*Depends on winding, frequency and lifetime required.
 Limited application of the motor driving against end stop is available under required technical and operating conditions. JE will provide specifics of such conditions upon request. JE will not be responsible for product warranty or any liabilities associated with the application of drive against end stop if such application is used without following JE's instructions.
 Radial forces on the shaft will reduce life time and performance.
 Note: All force and power output values are minimum values, at rated voltage and motor temperature 23°C.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1 : 2015
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	130 (B) according to DIN EN 60085 : 2008
Approval	standard
Mounting	any position
Electrical connection	connector type B, C, D
Protection	IP40 according to DIN EN 60529 : 2014
Weight	67 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

Order Reference

Type	Stepper Motor				UCE	13	N	01	D	1E
Configuration	13	bipolar, standard magnet	73	bipolar, stronger magnet						
	23	unipolar, standard magnet	83	unipolar, stronger magnet						
Approval	N									
Resistance	see next page, Resistance per winding for bipolar or unipolar									
Connection	B, C see next pages "Connection Types" D									
Shaft	1E Travel 13 mm ± 0.7 mm (other standard shafts see under dimensions)									

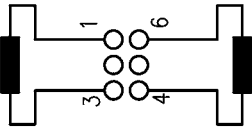
All specifications are representative only and maybe subject to variation. For confirmation of values, please contact Johnson Electric.
 Please also read "Saia Motors Important Notes" on catalog or at www.johnsonelectric.com/SaiaMotorsNotes



Technical Data

bipolar	Rated voltage U_N :	V	6	12	24
	Duty cycle	%	100	100	100
	Resistance R_{20}	Ω	24	90	380
	Winding code		05	02	01
unipolar	Rated voltage U_N :	V	6	12	24
	Duty cycle	%	100	100	100
	Resistance R_{20}	Ω	24	90	380
	Winding code		07	08	01
	Travel per step	mm	0.042		
	Winding temperature T_{max}	$^{\circ}C$	130		
	Axial play at ± 20 N force	mm	< 0.25		

Circuit diagram bipolar



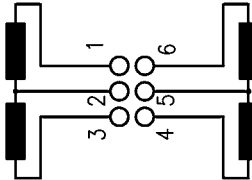
stepping sequence number

	I	II	III	IV	I
pin number 1	+	+	-	-	+
3	-	-	+	+	-
4	-	+	+	-	-
6	+	-	-	+	+

→ Pull in (step I to IV, I to IV, etc.)

← Push out (step IV to I, step IV to I, etc.)

unipolar



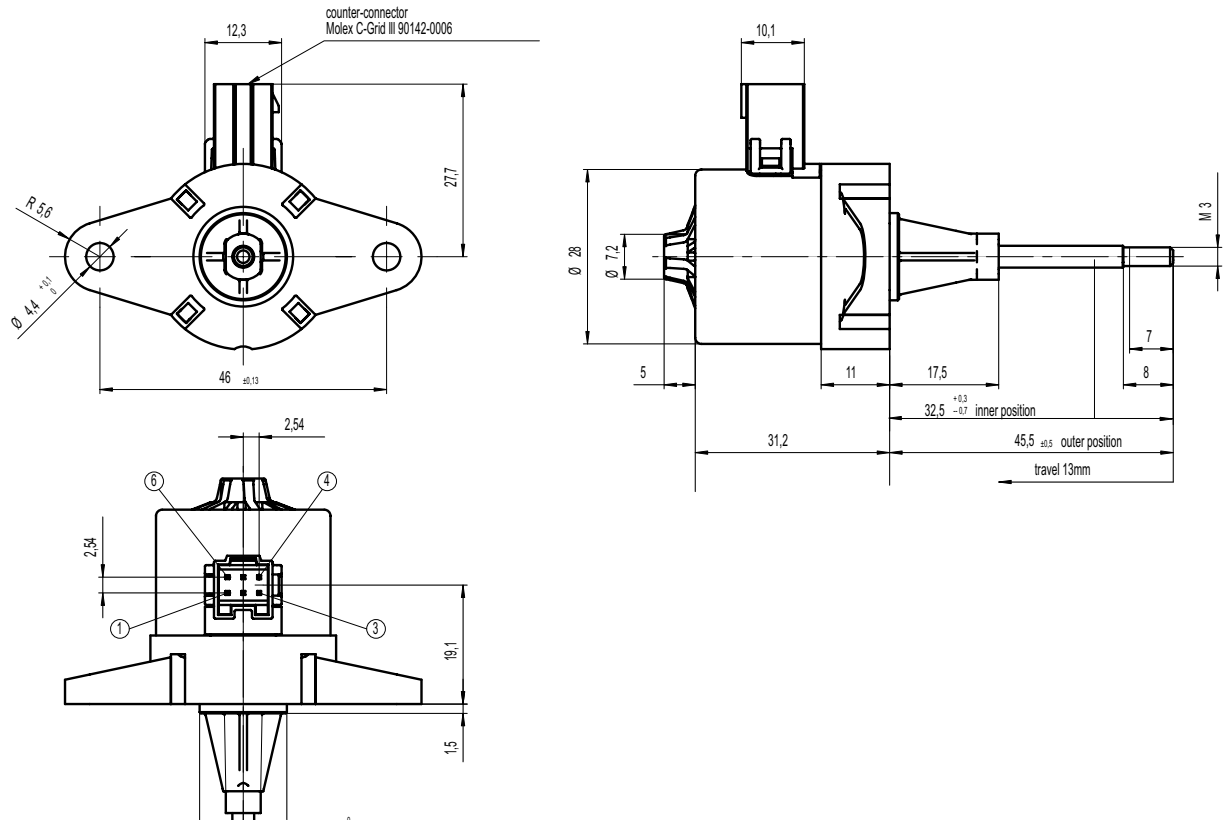
stepping sequence number

	I	II	III	IV	I
pin number 1	-	-			-
2	+	+	+	+	+
3			-	-	
4		-	-		
5	+	+	+	+	+
6	-			-	-

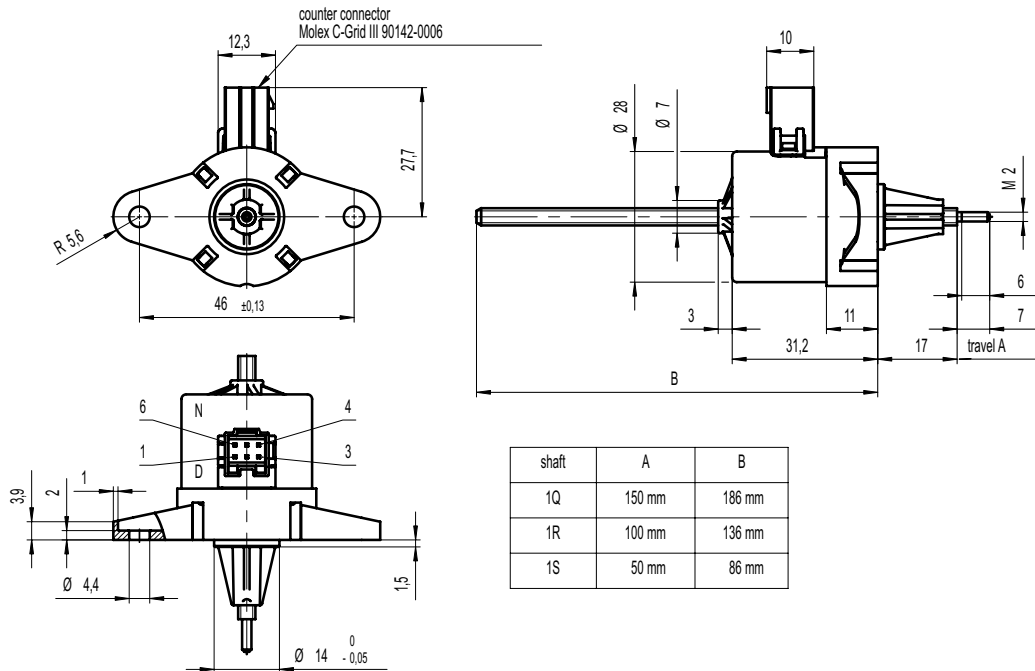
→ Pull in (step I to IV, I to IV, etc.)

← Push out (step IV to I, step IV to I, etc.)

Dimensions Version with Connector D, with 13 mm travel, shaft 1E



Version with Connector D, with 50..150 mm travel, shaft 1R, 1S, 1Q - only for pull operation



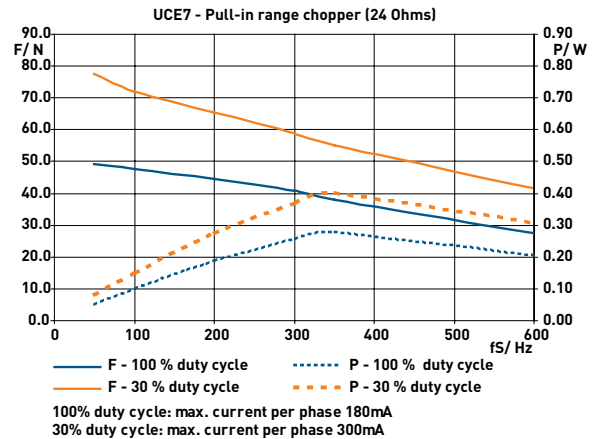
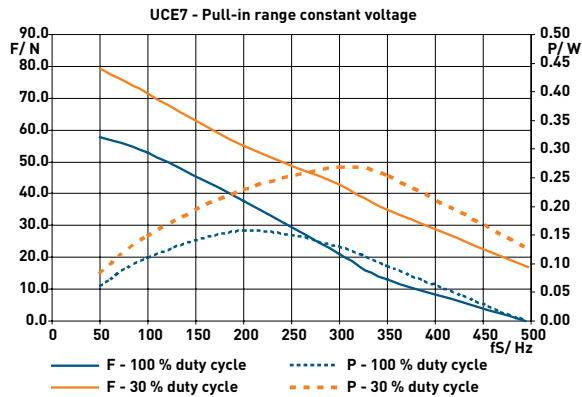
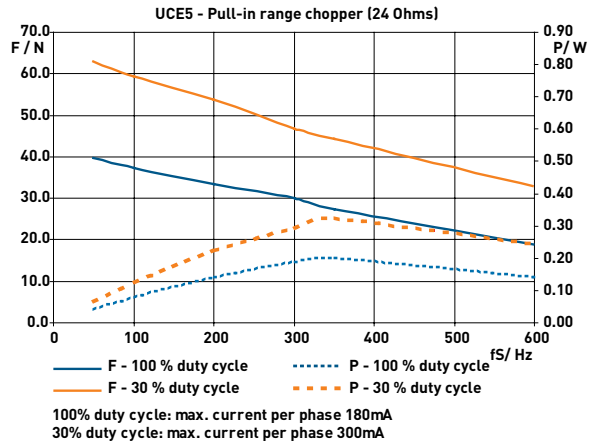
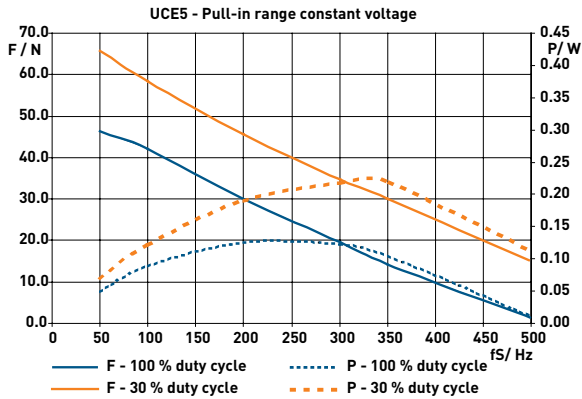
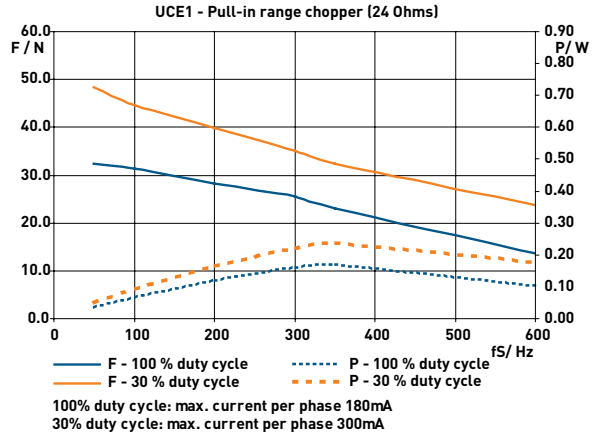
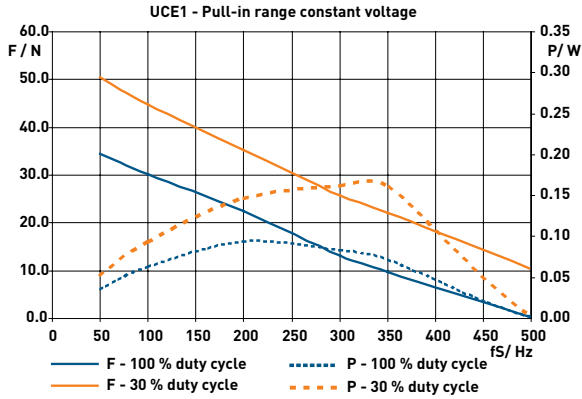
Please note:

The linear motor with non-captive shaft needs an external antirotation fixation and guidance. The antirotation is to produce the linear movement.

Application design of the guidance has to consider a maximum tolerance of 0.2° from the ideal axis.

The shaft guidance has strong influence on motor live time.

Performance Chart



Performance Chart

